

MODEL IDENTIFICATION AND ADAPTIVE SYSTEMS

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Answer the following questions:

- 1) Illustrate the main characteristics of an adaptive control algorithm and discuss the main issues involved in its design.
- 2) Discuss the computational complexity of the LMS algorithm.
- 3) Describe the linearized and extended Kalman filtering approaches, discussing their differences.
- 4) Describe the difference between comb and notch filters.

Instructions:

- Report your name and identification number on the top right corner of the first page.
- Use separate pages for answers to different questions (one page for each question).
- Books, course slides, notes are not allowed.