

MODEL IDENTIFICATION AND ADAPTIVE SYSTEMS

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Answer the following questions:

- 1) Discuss the difference between recursive and adaptive identification methods.
- 2) With reference to narrowband noise feedforward active noise control system, describe the waveform synthesis algorithm and discuss its limitations.
- 3) Describe the steady-state Kalman predictor.
- 4) Illustrate the nonlinear estimation problem when the input-output relationship is static.

Instructions:

- Report your name and identification number on the top right corner of the first page.
- Use separate pages for answers to different questions (one page for each question).
- Books, course slides, notes are not allowed.